

# BASIC ROBOT BUILDING

with  
**LEGO®**  
**Mindstorms®**  
**NXT 2.0**



**John Baichtal**



Loaded with step-by-step illustrations!

que®

FREE SAMPLE CHAPTER

SHARE WITH OTHERS





# **BASIC ROBOT BUILDING**

with **LEGO Mindstorms NXT 2.0**

John Baichtal

**que**<sup>®</sup>

800 East 96th Street,  
Indianapolis, Indiana 46240 USA

## Basic Robot Building with LEGO Mindstorms NXT 2.0

Copyright © 2013 by John Baichtal

All rights reserved. No part of this book shall be reproduced, stored in a retrieval system, or transmitted by any means, electronic, mechanical, photocopying, recording, or otherwise, without written permission from the publisher. No patent liability is assumed with respect to the use of the information contained herein. Although every precaution has been taken in the preparation of this book, the publisher and author assume no responsibility for errors or omissions. Nor is any liability assumed for damages resulting from the use of the information contained herein.

ISBN-10: 0-7897-5019-8

ISBN-13: 978-0-7897-5019-8

Library of Congress Cataloging-in-Publication data is on file.

Printed in the United States of America

First Printing: December 2012

### Trademarks

All terms mentioned in this book that are known to be trademarks or service marks have been appropriately capitalized. Que Publishing cannot attest to the accuracy of this information. Use of a term in this book should not be regarded as affecting the validity of any trademark or service mark.

### Warning and Disclaimer

Every effort has been made to make this book as complete and as accurate as possible, but no warranty or fitness is implied. The information provided is on an “as is” basis. The authors and the publisher shall have neither liability nor responsibility to any person or entity with respect to any loss or damages arising from the information contained in this book.

### Bulk Sales

Que Publishing offers excellent discounts on this book when ordered in quantity for bulk purchases or special sales. For more information, please contact

**U.S. Corporate and Government Sales**  
**1-800-382-3419**  
**corpsales@pearsontechgroup.com**

For sales outside of the U.S., please contact

**International Sales**  
**international@pearsoned.com**

#### Editor-in-Chief

Greg Wiegand

#### Executive Editor

Rick Kughen

#### Development Editor

Rick Kughen

#### Managing Editor

Sandra Schroeder

#### Project Editor

Seth Kerney

#### Copy Editor

Chuck Hutchinson

#### Indexer

Ken Johnson

#### Proofreader

Paula Lowell

#### Technical Editor

James F. Kelley

#### Publishing Coordinators

Cindy Teeters  
Romny French

#### Interior Designer

Mark Shirar

#### Cover Designer

Anne Jones

#### Composer

Trina Wurst

# Contents at a Glance

	Introduction	1
<b>CHAPTER 1</b>	Unboxing the LEGO Mindstorms NXT Set	7
<b>CHAPTER 2</b>	Project: Backscratcher Bot	37
<b>CHAPTER 3</b>	Anatomy of the NXT Brick	57
<b>CHAPTER 4</b>	Introduction to Programming	81
<b>CHAPTER 5</b>	Project: Clothesline Cruiser	95
<b>CHAPTER 6</b>	Building Stronger Models	123
<b>CHAPTER 7</b>	Know Your Sensors	131
<b>CHAPTER 8</b>	Advanced Programming	143
<b>CHAPTER 9</b>	Project: Rebounder	157
<b>CHAPTER 10</b>	Expanding on Mindstorms	181
	Glossary	195
	Index	201

# Table of Contents

## Introduction 1

Conventions Used in This Book 4

Special Elements 4

## Chapter 1 Unboxing the LEGO Mindstorms NXT Set 7

The Box 7

Under the Flap 8

Opening the Box 9

The Contents 9

Reading Material 10

Connector Pegs 11

3M Connector Pegs 12

Connector Pegs with Bushing 13

Connector Pegs with Cross-Axle Ends 14

2M Axle Peg 14

Connector Peg with Towball 15

1/2 Connector Pegs 16

Bushings 16

Cross Axles 17

Cross Axles with End Stops 18

Wheels and Treads 19

Gears 20

Teeth 21

Balls 21

Beams With Pegs 22

Beams 23

Angle Beams 24

Car Parts 25

Steering Links 26

Angle Elements 26

Cross-Axle Connectors 27

Cross Blocks 27

More Miscellaneous Parts 28

	Peg Joiner	29
	Motors, Wires, and Sensors	31
	USB Cable	34
	Mindstorms Wires	35
	The NXT Brick	35
	Next Chapter	36
<b>Chapter 2</b>	<b>Project: Backscratcher Bot</b>	<b>37</b>
	Adding Batteries to the NXT Brick	38
	Parts You Need	40
	Step-by-Step Assembly Instructions	42
	Programming the Backscratcher Bot	49
	Running the Backscratcher Bot	56
	Next Chapter	56
<b>Chapter 3</b>	<b>Anatomy of the NXT Brick</b>	<b>57</b>
	The Brick	58
	Buttons	59
	Ports	59
	Connector Holes	61
	Reset Button	62
	Menus	63
	My Files	63
	NXT Program	66
	Try Me	67
	The View Menu	68
	NXT Datalog	70
	Settings	70
	Bluetooth	73
	Powering Your NXT	77
	Resetting a Crash	78
	Updating NXT Firmware	78
	The Next Chapter	79
<b>Chapter 4</b>	<b>Introduction to Programming</b>	<b>81</b>
	System Requirements	82
	Installing the Software	83

	Installing on a PC	83
	Installing on a Mac	84
	NXT-G 101	85
	The Programming Block	85
	Commonplace Blocks	87
	Programming the Backscratcher Bot	92
	Create the Program	92
	Connect to the NXT Brick	93
	Download the Program	94
	The Next Chapter	94
<b>Chapter 5</b>	<b>Project: Clothesline Cruiser</b>	<b>95</b>
	Parts You Need	96
	Step-by-Step Instructions	97
	Programming the Clothesline Cruiser	119
	Setting Up the Clothesline	120
	What to Do With Your Cruiser?	121
	The Next Chapter	122
<b>Chapter 6</b>	<b>Building Stronger Models</b>	<b>123</b>
	Use Multiple Pegs	123
	Connect Each Part to as Many Others as Possible	123
	Reinforce Corners with Angle Beams	124
	Use Combination Parts and Cross Blocks	124
	Attach Cross Axles	125
	Combine Technic and System Bricks	126
	Use Chassis Bricks	128
	The Next Chapter	129
<b>Chapter 7</b>	<b>Know Your Sensors</b>	<b>131</b>
	Mindstorms Sensors	131
	Touch Sensors	132
	Ultrasonic Sensors	133
	Color Sensors	133
	Sound Sensor	134
	Motor	135
	Calibrating Sensors	136

	<b>Third-Party Sensors</b>	137
	Compass Sensor	138
	Passive Infrared (PIR) Sensor	138
	Wi-Fi Sensor	138
	Magnetic Sensor	139
	Flex Sensor	139
	Voltage Sensor	140
	Barometric Sensor	140
	Inertial Motion Sensor	140
	<b>The Next Chapter</b>	141
<b>Chapter 8</b>	<b>Advanced Programming</b>	<b>143</b>
	<b>Data Wires</b>	144
	Green Wires	144
	Yellow Wires	145
	Orange Wires	145
	Gray Wires	146
	<b>Connecting Wires</b>	147
	<b>Additional Blocks</b>	148
	Variable Block	148
	Constant Block	149
	Random Block	150
	Keep Alive Block	150
	Light Sensor Block	151
	Rotation Sensor Block	151
	Display Block	152
	Bluetooth Block	152
	Logic Block	153
	<b>Creating Your Own Blocks</b>	154
	<b>The Next Chapter</b>	156
<b>Chapter 9</b>	<b>Project: Rebounder</b>	<b>157</b>
	Parts You Need	158
	Step-by-Step Instructions	159
	A Note About Tank Treads	175
	Programming the Rebounder	176
	<b>The Next Chapter</b>	180

**Chapter 10 Expanding on Mindstorms 181**

Read Blogs 181

The NXT STEP 181

Mindstorms 182

Design Virtual Models 183

Attend Gatherings 184

LUGs 185

Conventions 185

FIRST LEGO League 186

Read *BrickJournal* 188

Expand Your Collection 188

Bricklink 189

Pick a Brick 189

LEGO Education 189

Third-Party Brick Makers 190

Omni Wheels 190

Bricktronics 190

Tetrix 191

Print Your Own 192

**Glossary 195****Index 201**

## About the Author

**John Baichtal** is a contributor to *MAKE* magazine and Wired's GeekDad blog. He is the co-author of *The Cult of LEGO* (No Starch) and author of *Hack This: 24 Incredible Hackerspace Projects from the DIY Movement* (Que). Most recently he wrote *Make: Lego and Arduino Projects for MAKE*, collaborating with Adam Wolf and Matthew Beckler. He lives in Minneapolis, Minnesota, with his wife and three children.

## Dedication

This book is dedicated to my lovely wife Elise and my LEGO-obsessed kids. Sorry about all the robots cluttering up the house!

## Acknowledgments

I'd like to thank my editor, Rick Kughen, and my frequent collaborator, Adam Wolf, for their help with this book.



## We Want to Hear from You!

As the reader of this book, *you* are our most important critic and commentator. We value your opinion and want to know what we're doing right, what we could do better, what areas you'd like to see us publish in, and any other words of wisdom you're willing to pass our way.

We welcome your comments. You can email or write to let us know what you did or didn't like about this book—as well as what we can do to make our books better.

*Please note that we cannot help you with technical problems related to the topic of this book.*

When you write, please be sure to include this book's title and author as well as your name and email address. We will carefully review your comments and share them with the author and editors who worked on the book.

Email: [feedback@quepublishing.com](mailto:feedback@quepublishing.com)

Mail: Que Publishing  
ATTN: Reader Feedback  
800 East 96th Street  
Indianapolis, IN 46240 USA

## Reader Services

Visit our website and register this book at [quepublishing.com/register](http://quepublishing.com/register) for convenient access to any updates, downloads, or errata that might be available for this book.



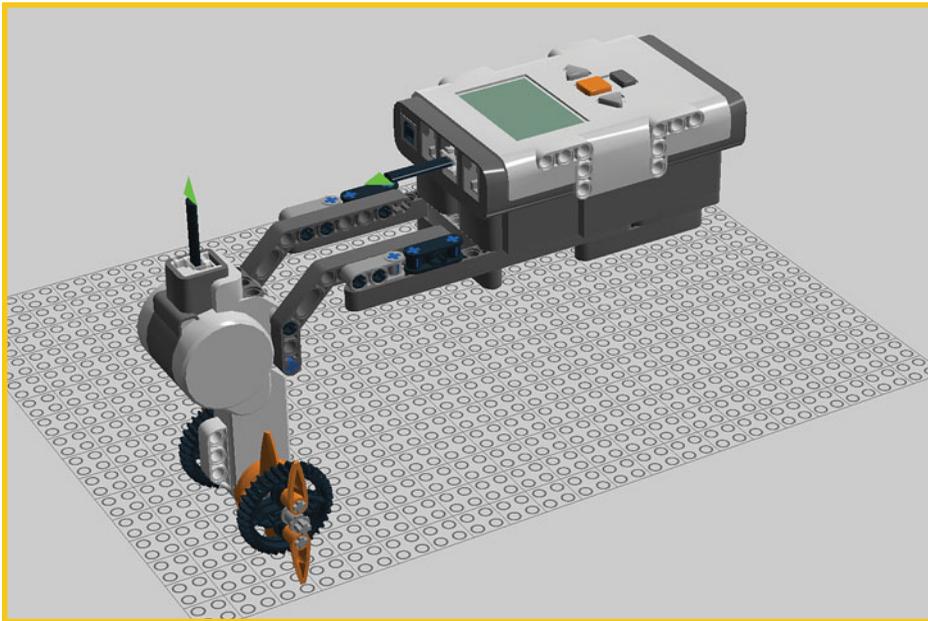
# Introduction

You're holding the most amazing building set in the world. Now what?

It can be a little intimidating, when faced with all those possibilities. Mindstorms has built up such a massive following that a veritable ecosystem has developed—modelmakers sharing their design files, programmers creating new blocks, and conventions gathering together builders from around the world. What could you do with all of that? The easy answer is, a lot. The more challenging question is, where do you begin in such a vast pool of knowledge? The aim of this book is to simplify the experience and make it easy and fun.

*Basic Robot Building with LEGO Mindstorms NXT 2.0* shows you how to build three easy models, using only the parts found in a LEGO Mindstorms NXT 2.0 boxed set. Everything you need is in this book and your set!

How can we do projects with Mindstorms without knowing what's in the set? In Chapter 1, "Unboxing the LEGO Mindstorms NXT Set," I break down everything you get as we unbox the entire set.



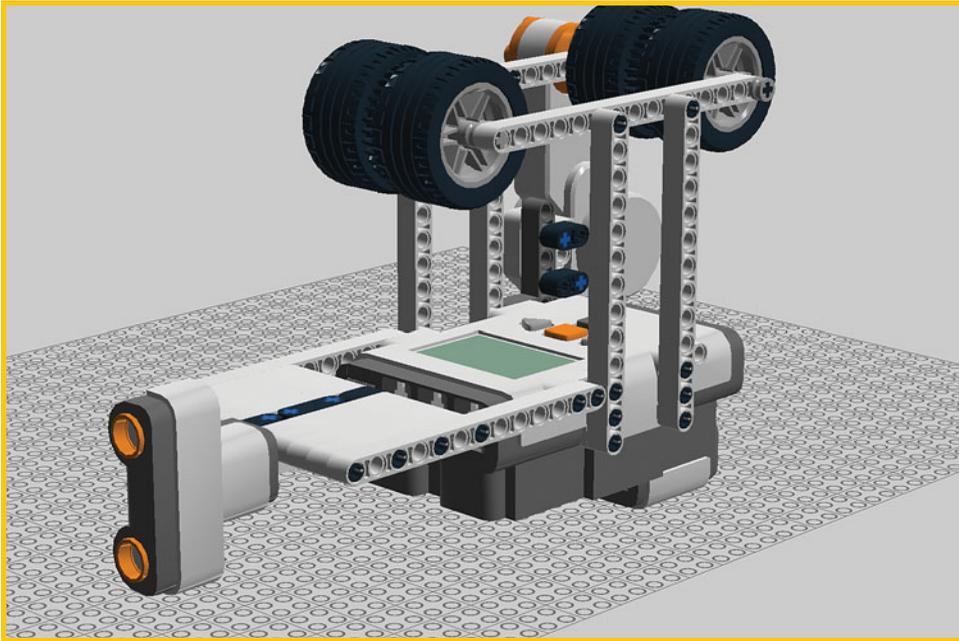
**FIGURE I.1** Build the Backscratcher Bot and cure itchy backs forever!

In Chapter 2, “Project: Backscratcher Bot,” we dive in the deep end of the LEGO pool as we build our first robot, a portable Backscratcher Bot (see Figure I.1) that needs no programming know-how to get working.

The most important element in the set is the NXT brick, a clever miniature computer that controls the motors and sensors and helps you turn a pile of plastic bricks into a robot. In Chapter 3, “Anatomy of the NXT Brick,” we’ll delve into the NXT and examine all of its capabilities and menus.

To reach the full potential of the NXT, however, we’ll have to learn how to program it. In Chapter 4, “Introduction to Programming,” we’ll examine NXT-G, the Mindstorms programming environment, and write our first program.

Then it’s time for our next robot! Chapter 5, “Project: Clothesline Cruiser,” provides instructions on building the Clothesline Cruiser (see Figure I.2), a robot that travels via rope! We’ll also program the robot to control its movements.



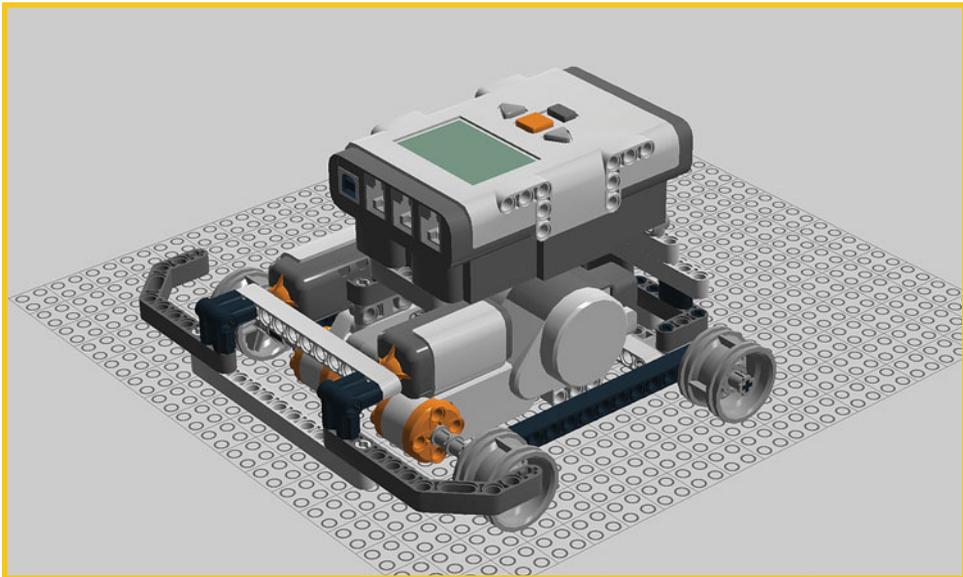
**FIGURE I.2** The Clothesline Cruiser transports itself along a length of clothesline.

After we've got a couple of robots under our belts, we'll delve deeper into the mysteries of Mindstorms! Chapter 6, "Building Stronger Models," introduces you to advanced building techniques, offering tips on building stronger and smarter models.

Chapter 7, "Know Your Sensors," immerses you in the world of sensors, those electronic gadgets that plug into the NXT brick and send it data. You can use sensors to do everything from judging distance to detecting an object's color. Let's find out how they work and what they can do!

Chapter 8, "Advanced Programming," offers advanced programming techniques, introducing you to a bevy of concepts to help you make your robots even cooler!

We get to put these techniques to the test in Chapter 9, "Project: Rebounder," in which we build our third and final robot. The Rebounder (see Figure I.3) is miniature tank-treaded robot that rolls around blissfully, then rebounds when it bumps into something.



**FIGURE I.3** The Rebounder is an autonomous robot that reacts to walls by moving away from them.

Finally, Chapter 10, “Expanding on Mindstorms,” suggests some next steps for advancing your LEGO knowledge, as well as expanding your supply of parts. The Mindstorms ecosystem is vast, and I’ll show you how to smartly expand your capabilities.

There you have it. Mastering LEGO Mindstorms is a rewarding journey that teaches you about everything from mechanical engineering to computer programming. Let’s get started!

## Conventions Used in This Book

I think this book should be fairly easy to figure out without much explanation from me, although there are a few teaching tools I use along the way that deserve some discussion here.

### Special Elements

This book includes a few special elements that provide additional information not included in the basic text. These elements are designed to supplement the text to help you get up to speed with your LEGO Mindstorms NXT 2.0 quickly and easily.

## TIP

A *tip* is a piece of advice that helps you accomplish a task—whether it be a hands-on building task or a programming chore—easily and with little to no heartache.

## NOTE

A *note* is designed to provide information that is useful and/or interesting but not crucial for the task at hand. Notes often contain ancillary information that is good to know, but won't be crippling if you skip it.

## CAUTION

A *caution* is the publishing equivalent of a big, red stop sign. When you see one of these, read it and do what it says! Failure to do so can have a variety of repercussions—all the way from a Mindstorms bot that doesn't work, to a potentially dangerous situation.

## SIDEBAR

### Some Extra Thoughts

Sidebars are where I've tucked information that is relevant, but slightly off-task or non-essential, such as juicy bits of background and behind-the-scenes info on LEGO Mindstorms.

*This page intentionally left blank*



# Unboxing the LEGO Mindstorms NXT Set

When you drooled over product photos on the Mindstorms box or dug through the parts inside, no doubt you found the breadth and complexity of the parts a little unnerving. Looking at all those LEGO beams and connectors can be a little intimidating, not knowing what they're for or how they fit together. In this chapter, we look at every part that comes with the set and talk a little about each one.

## The Box

The LEGO Mindstorms NXT 2.0 box (see Figure 1.1) intrigues with all the cool possibilities you can imagine are inside, not the least of which are the great—albeit complex—models LEGO shows you how to make with the set. The headliner is Alpha Rex, the humanoid robot in the center of the box. There's a little science fiction in the rendering; the color sensor doesn't actually emit a visible beam of light, and the eyes, which are the ultrasonic sensor, don't actually light up.



A little creative license was used here...

**FIGURE 1.1** The LEGO Mindstorms NXT 2.0 box.

Still, you can actually build the Alpha Rex, following the instructions contained in the Mindstorms software that came with the set.

## NOTE

### Alpha Rex Directions

I didn't include directions for building Alpha Rex in this book because instructions for building this bot are included with the set. Instead, I focused on building three bots that aren't detailed in the instructions. That means between this book and the instructions that came with the set, you now have details on how to build *seven different bots!*

## Under the Flap

LEGO is really good about dressing up the box with tantalizing glimpses of the contents, all the better to get customers to reach for their wallet (see Figure 1.2). Looking at all those beautiful parts and robots displayed, how could you not buy the set?



**FIGURE 1.2** This is 100% pure geeky goodness.

This great artwork is also educational, explaining the difference between the sensors and giving a brief intro on how programming works. What I found most exciting is the huge spread showing all the components that come with the set.

## Opening the Box

Cracking open the box, you see a bunch of plastic bags of LEGO parts stuffed into the box (see Figure 1.3). You'll very quickly realize the Mindstorms box is probably not a container that you can use long term for storing your set, particularly if you use it a lot. While pretty, it's merely a cardboard box with no dividers or reinforcement, so it will get squashed very quickly.



**FIGURE 1.3** From “wow” to “ho-hum,” the inside of the Mindstorms box is, well, just a box.

## The Contents

Next, let's dump out everything inside the box (see Figure 1.4). Look at all this cool stuff! The plastic bags hold the LEGO beams and connectors, and the white cardboard boxes hold the NXT brick and the sensors, motors, and wires. When you look at the parts like this, it doesn't seem like a \$280 set, but when you start building cool robots, you'll think differently.



**FIGURE 1.4** Mindstorms parts—just add imagination.

## WHAT YOU DON'T GET WITH THE SET

There is a lot of cool stuff that LEGO has not seen fit to include in the set. For instance, there is a huge variety of gears available that you'll never find in the basic Mindstorms set. You might also notice that the parts found in the set are fairly blah when it comes to color. Be sure to read Chapter 10, "Expanding on Mindstorms," in which I discuss where to find all sorts of parts to expand upon Mindstorms' possibilities.

## Reading Material

Let's dive in! First, let's begin with the printed stuff that comes with the set, as shown in Figure 1.5. The Test Pad, on the left, is a poster-sized track that you can use with a rolling robot. It has a circuit that you can use to test a line-following robot, as well as color switches to test its color sensor. The stickers are just for looks, obviously, and are used to dress up the four default models that LEGO suggests you make with the set. The *LEGO Mindstorms User Guide* offers basic instructions on how to build robots and program them, and the disc holds the software you need to do so. We talk more about the disc and its programs in Chapter 4, "Introduction to Programming."



**FIGURE 1.5** The user guide and other materials included with the set.

## Connector Pegs

In many ways, these little tubes—*connector pegs* in LEGO parlance—are the glue that holds your robot together (see Figure 1.6). The pegs connect two LEGO elements via their holes, and you'll use them all the time. Interestingly, the black and gray pegs are nearly identical and in many cases can be used interchangeably. The critical difference between the two is that the black pegs have little ridges on them that add friction, to reduce the tendency of a single peg to rotate on its own. By contrast, the gray pegs are smooth and can be used as axles. You get 88 black pegs with your set and 6 gray ones.

### NOTE

#### Your Mileage May Vary

You might get a different number of parts than what I detail here. For example, I got seven gray connector pegs in my set. Even LEGO's vaunted quality control messes up sometimes!



Gray pegs are smooth and can be used as axles

Black pegs have ridges that deter rotation

**FIGURE 1.6** Black and gray connector pegs are the backbone of your Mindstorms set.

## 3M Connector Pegs

More pegs! The big ones shown in Figure 1.7, called *3M connector pegs*, are a lot like the black and gray ones in Figure 1.6, but they extend three standard LEGO thicknesses. In LEGO parlance, this is referred to as *3M*—the thickness of three regular LEGO beams stacked atop each other.

### TIP

#### M Refers to Length, Too

Here, the M number refers to the *length* of an element, so a 3M connector peg is the same length as three beams stacked on top of each other.

The blue pegs have friction ridges, whereas the beige ones do not. The set includes 52 blue pegs and 6 beige ones.



Beige connector  
pegs are smooth

Blue connector pegs  
have friction ridges

**FIGURE 1.7** The longer connectors are delineated by both color and presence (or lack thereof) of friction ridges.

## Connector Pegs with Bushing

The next type of peg is rather interesting. You may not use them all of the time, but when you need them you'll totally be grateful to have them. They're basically two-thickness pegs, but have a cross-axle bushing on the end (see Figure 1.8). This is a special connector that accommodates Mindstorms' cross axles, so you could use one to anchor the hub of a wheel, for instance. Another great use of the part is as an easily removable peg. Say you want to keep a moving part of your robot from moving; you could temporarily block the motion with one of these pegs, leaving the big part—the bushing—sticking out so you can easily grab and remove it when you're ready. You get 10 of these in the set.



**FIGURE 1.8** These connectors combine a peg with a bushing!

## Connector Pegs with Cross-Axle Ends

You might have figured out by now that the Mindstorms set comes with lots of types of pegs! Figure 1.9 shows even more pegs; these pegs have a regular connector on one side and a cross connector on the other. In this book I call those *cross connectors*. You'll find yourself using these almost as much as the black ones previously shown in Figure 1.6. They're important because some LEGO beams have cross-axle holes as well as the regular round kind. As with the 3M pegs previously shown in Figure 1.7, the blue color signifies that those pegs have friction ridges, whereas the beige ones do not. The cross-axle portion is the same for both types. You'll find 24 blue pegs of this type in the set, along with 4 beige ones.



**FIGURE 1.9** These pegs allow you to join two elements, one with a Technic hole and one with a cross hole.

## 2M Axle Peg

The 2M axle peg shown in Figure 1.10 is another commonplace one and is essentially like the ones previously shown in Figure 1.9, but these pegs are all cross axle. The 2M axle pegs are two standard LEGO thicknesses long. Nine of them come in the box.

### TIP

#### Extricating a 2M Axle Peg

The 2M axle pegs have a tendency to get “lost” when you use them to hold two beams together. To remove one of these pegs, poke the end with a cross axle to push it out.



**FIGURE 1.10** 2M axle pegs.

## Connector Peg with Towball

Next comes the connector peg with towball. These pegs are typically used as an end-stop for some sort of movement. If you need a LEGO part sticking out to make sure your robot's range of movement is limited, you'll want one of these pegs. Another use is as a holder for a rubber band. Say you want to have a hinged piece held taut to keep it from flapping around. Simply attach one of these pegs to each side and loop a rubber band around the towball (see the Alpha Rex's hands on the cover of your box). As you can see from Figure 1.11, the gray ones have a cross-axle connector, and the black ones have a smooth connector. You get 10 black pegs and 2 gray ones.



**FIGURE 1.11** If you've ever used a ball hitch to tow a boat or trailer, these connectors will look quite familiar to you.

## 1/2 Connector Pegs

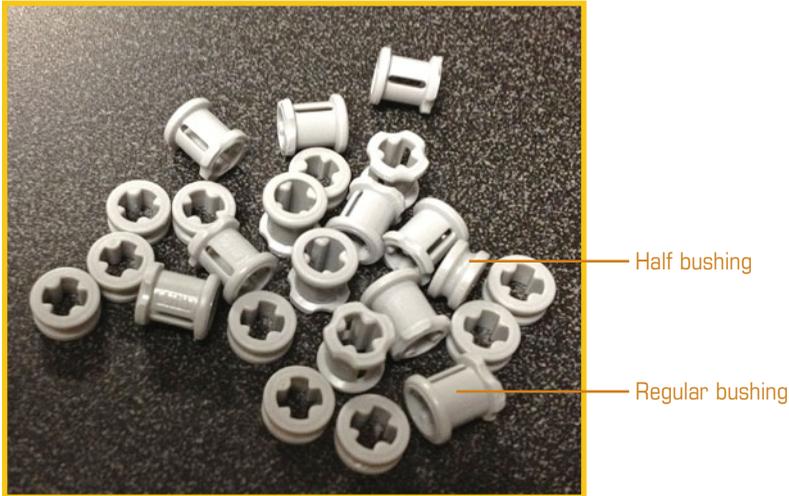
The final type of peg you'll find in the set is the 1/2 connector peg, shown in Figure 1.12. Just three of these pegs are included in the set. They look a lot like half of a gray connector peg. Pure and simple, these pegs provide a way of turning a beam's hole into a standard LEGO stud. You insert the long end into a hole, leaving the stud sticking out, allowing you to attach a regular LEGO brick to the stud. The connection isn't strong, and it is typically used more for cosmetic purposes than structural ones.



**FIGURE 1.12** Use these pegs to transform a Technic hole into a LEGO stud.

## Bushings

Next, let's look at *bushings*, which are little tubes that secure the ends of cross axles. You'll use them for pretty much every Mindstorms model you'll ever make (see Figure 1.13). Bushings come in two flavors: bushings and half bushings. The former are one LEGO thickness, and the half bushings are half as thick. With bushings, unlike most of the parts you'll find in the set, LEGO doesn't differentiate the two types with different colors, although you'll often find half bushings in bright yellow in different sets. There are 11 bushings and 9 half bushings in the Mindstorms set.



**FIGURE 1.13** Bushings are an integral part of nearly any Mindstorms model you create.

## Cross Axles

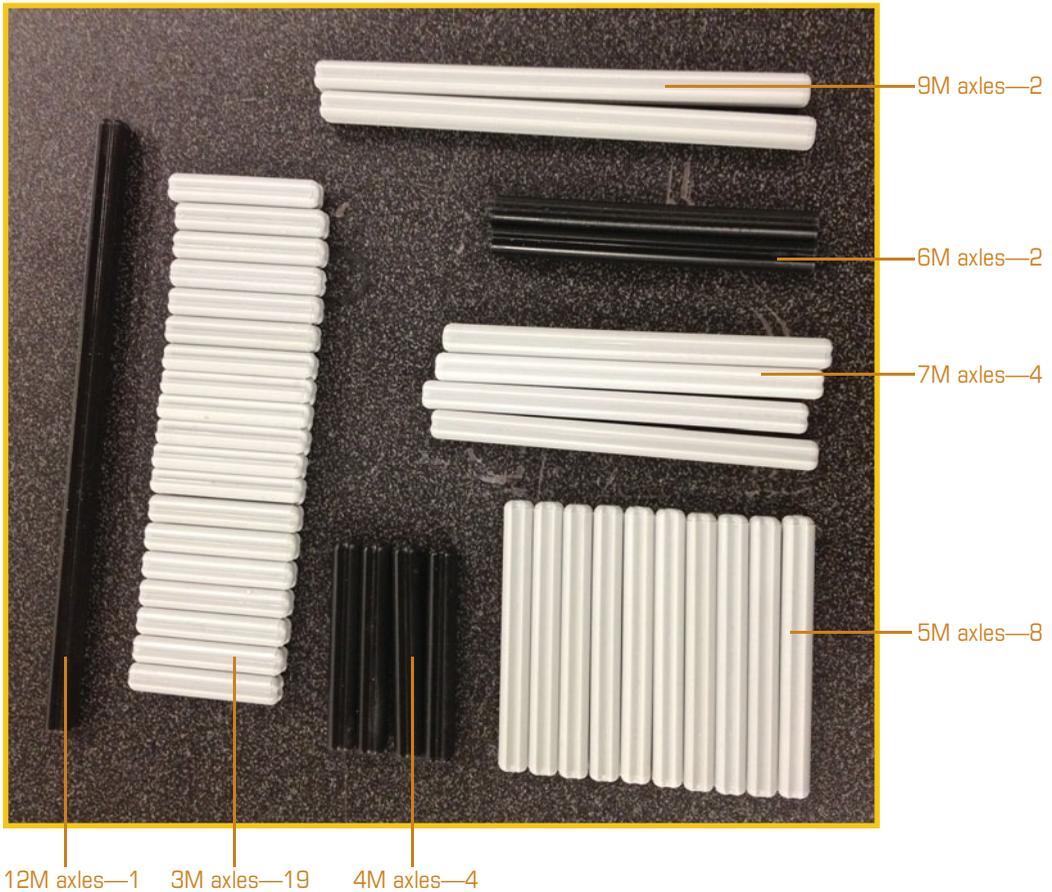
Now, for the famous cross axles you’ve been hearing about so much. Cross axles, shown in Figure 1.14, are absolutely critical components of the Mindstorms set, used for everything from stabilizers securing multiple thicknesses of beam to, well, serving as axles for wheels. The set includes the following cross axles:

### NOTE

#### M Stands for Thickness and Length

As we discussed earlier, the “M” refers to the width of a standard LEGO brick. So, 3M is equal to the width of three standard bricks lined up side by side. But wait! Mindstorms also uses the M measurement to indicate length, so the 7M cross axle is the same length as the width of seven beams.

- 12M axles—1
- 9M axles—2
- 7M axles—4
- 6M axles—2
- 5M axles—8
- 4M axles—4
- 3M axles—19

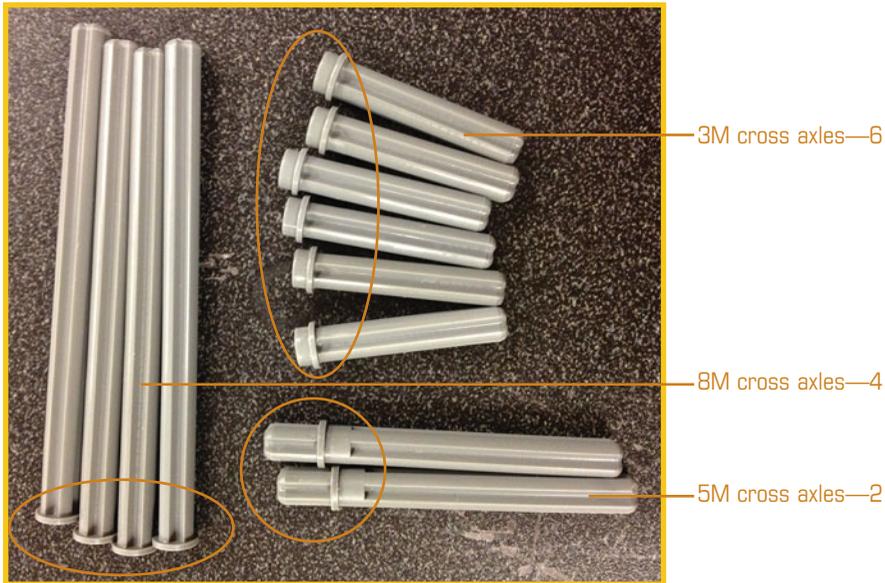


**FIGURE 1.14** Cross axles are your new best friend.

## Cross Axles with End Stops

The next piece is a variant of the cross axle, which features end stops so you don't have to use a bushing to keep parts from sliding off the end (see Figure 1.15). You'd be surprised how often this piece will come in handy! The set includes three different types of axles, and each features a different type of end stop. The set contains

- 3M cross axles—6
- 5M cross axles—2
- 8M cross axles—4



**FIGURE 1.15** End stops on these axles eliminate the need for a bushing. Note that the end stops are circled in this photo.

## Wheels and Treads

Wheels and treads come next (see Figure 1.16). The set contains four rims along with rubber tires. You also get two tank treads that are compatible with the rims.



**FIGURE 1.16** Where the rubber meets the road.

## Gears

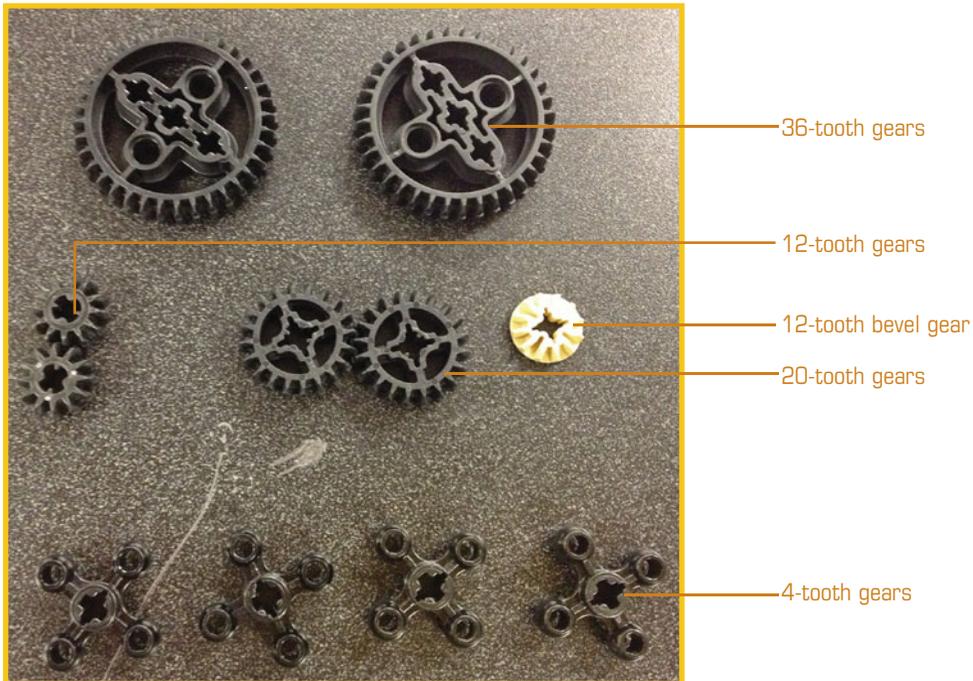
My favorite parts of any LEGO set are the gears. I love figuring out how to mesh them together in a clever way. It is a bit disappointing, though, that LEGO includes a rather weak assortment of gears in the set (see Figure 1.17). You get a mere 11 gears:

- 36-tooth gears—2
- 20-tooth gears—2
- 12-tooth gears—2
- 12-tooth bevel gear—1
- 4-tooth gears—4

### TIP

#### Gearheads Needn't Worry

If you, like me, yearn for more gear options, be sure to read Chapter 10, “Expanding on Mindstorms,” where I talk about where to find more.



**FIGURE 1.17** The Mindstorms set comes with a disappointing number of gears.

## Teeth

The next parts, *Bionicle teeth*, are kind of unusual for Mindstorms in that they're almost completely cosmetic. You get 10 of them in the set (see Figure 1.18). Although they're usually decorative, another possibility might be to use them in conjunction with a motor to serve as some sort of dial, rotating to a certain direction as directed by the NXT brick. Also, in the Backscratcher Bot, our first project in this book, we use the teeth as the business end of the scratcher; they're what scratch your back!



**FIGURE 1.18** These teeth are mostly for fun, but if you're clever, you can come up with other more useful applications.

## Balls

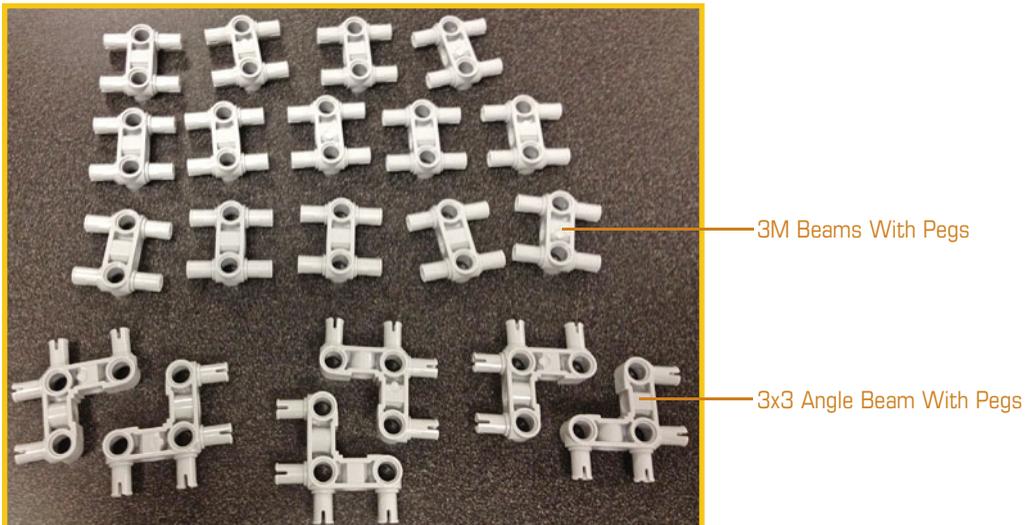
LEGO includes multicolored balls with the set, used by robots either as missiles or as objects to be color-scanned and sorted (see Figure 1.19). One common type of robot to use these balls is a Great Ball Contraption. These complex linked robots are often found at LEGO conventions. Some assemblies are so huge that they cover multiple tables and spend their time rolling, pulling, lifting, and shooting the balls in an endless chain reaction. You get three of each color ball with your set.



**FIGURE 1.19** These colored balls provide a variety of interesting possibilities.

## Beams With Pegs

The so-called beams with pegs are essentially short Mindstorms beams with connector pegs sticking out (see Figure 1.20). You can add them as stabilizers to a wobbly model, and they're also great for changing the angle of the beams because most LEGO beams have holes on two sides only. That means you sometimes have to resort to trickery to attach parts to the smooth sides. You get six of the angle beams and 14 of the 3M beams. I wish the set included more; I use them all the time!

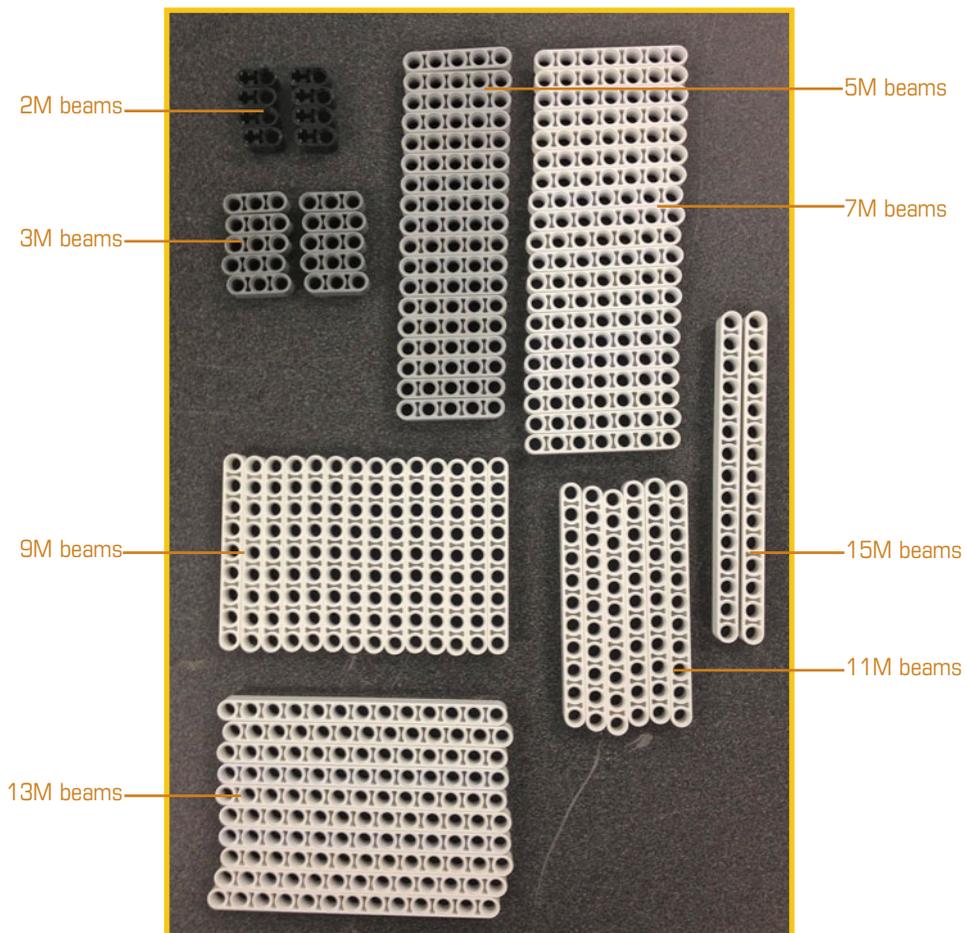


**FIGURE 1.20** Crafty builders make good use of beams with pegs.

## Beams

Next, let's check out beams, the bones of Mindstorms robots. Using these building blocks, you can pretty much create whatever you want—with the help of the other components, of course! The kit comes with the following beams (see Figure 1.21):

- 2M beams—8
- 3M beams—10
- 5M beams—18
- 7M beams—20
- 9M beams—14
- 11M beams—6
- 13M beams—10
- 15M beams—2



**FIGURE 1.21** Beams form the skeleton of any Mindstorms bot.

## Angle Beams

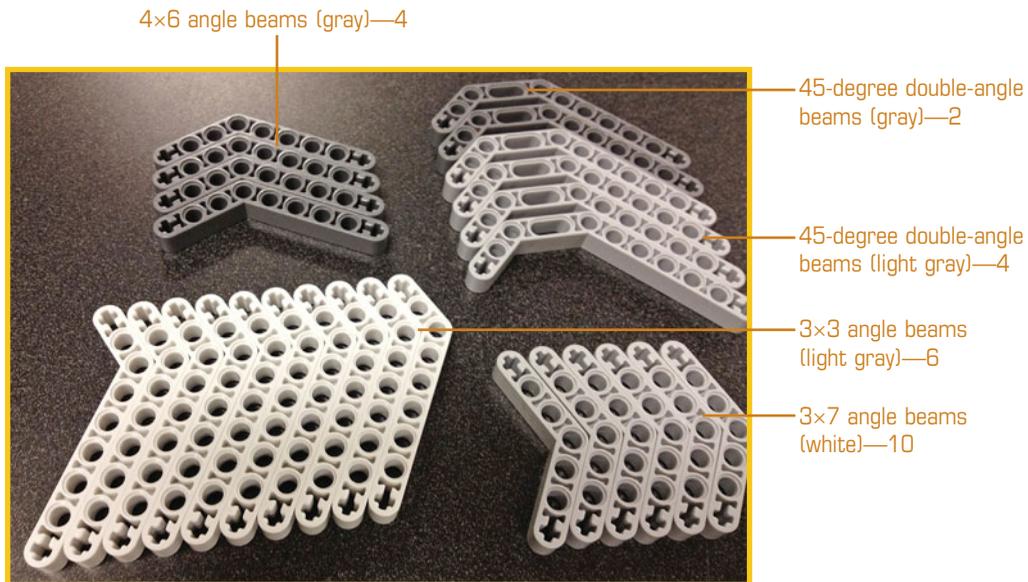
*Angle beams* add critical stability, enabling you to connect parts in ways that a straight beam cannot. For instance, you could reinforce the corners of a square robot with a 90-degree beam on each corner.

The orange parts in Figure 1.22 are the same as the similar-appearing dark gray parts, one of the few instances in the set where you get two basically identical parts sporting different colors. As you can see in Figures 1.22 and 1.23, the set includes

- 3×5 90-degree angle beams (gray)—14
- 2×4 90-degree angle beams (gray)—13
- 2×4 90-degree angle beams (orange)—4
- T-shaped angle beams—2
- 45-degree double-angle beams (medium gray)—2
- 45-degree double-angle beams (light gray)—4
- 3×3 angle beams (gray)—6
- 3×7 angle beams (white)—10
- 4×6 angle beams (white)—4



**FIGURE 1.22** L- and T-shaped angle beams provide stability and provide lots of building options.



**FIGURE 1.23** These angle beams help break your robot out of the 90-degree mindset.

## Car Parts

The parts shown in Figure 1.24 are purely cosmetic, made to make robotic cars more cool looking but not adding a lot of value. Essentially, what you're getting are the fenders and side panels of a car's body. As with other cosmetic parts, what you get out of them depends on your own cleverness. Who knows what functional mechanisms could be created?



**FIGURE 1.24** While purely cosmetic in nature, these parts will help you trick out any robotic cars you decide to build.

## Steering Links

The parts shown in Figure 1.25 are called *steering links*, and they're used in conjunction with tow balls to form a flexible link between two elements.



**FIGURE 1.25** Steering links offer a more flexible connection than beams.

## Angle Elements

The parts shown in Figure 1.26, called *angle elements*, are used for connecting cross axes, cross connectors, and connector pegs. Not only can you connect two axes to make a bigger one, you can use them structurally with axes to make cubes, triangles, and so on.

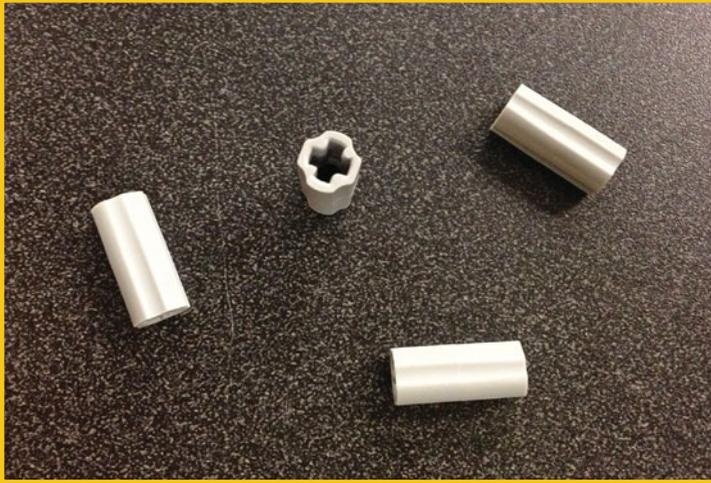
- 0-degree angle elements—5
- 90-degree angle elements—12
- 180-degree angle elements—6



**FIGURE 1.26** Angle elements help connect cross axes at different angles.

## Cross-Axle Connectors

Cross-axle connectors combine two cross axles into a longer one (see Figure 1.27). They also interface with other elements with cross ends. They're the sort of element you may not use a lot, but when you need one, you'll be grateful LEGO created them! You get four in the set.

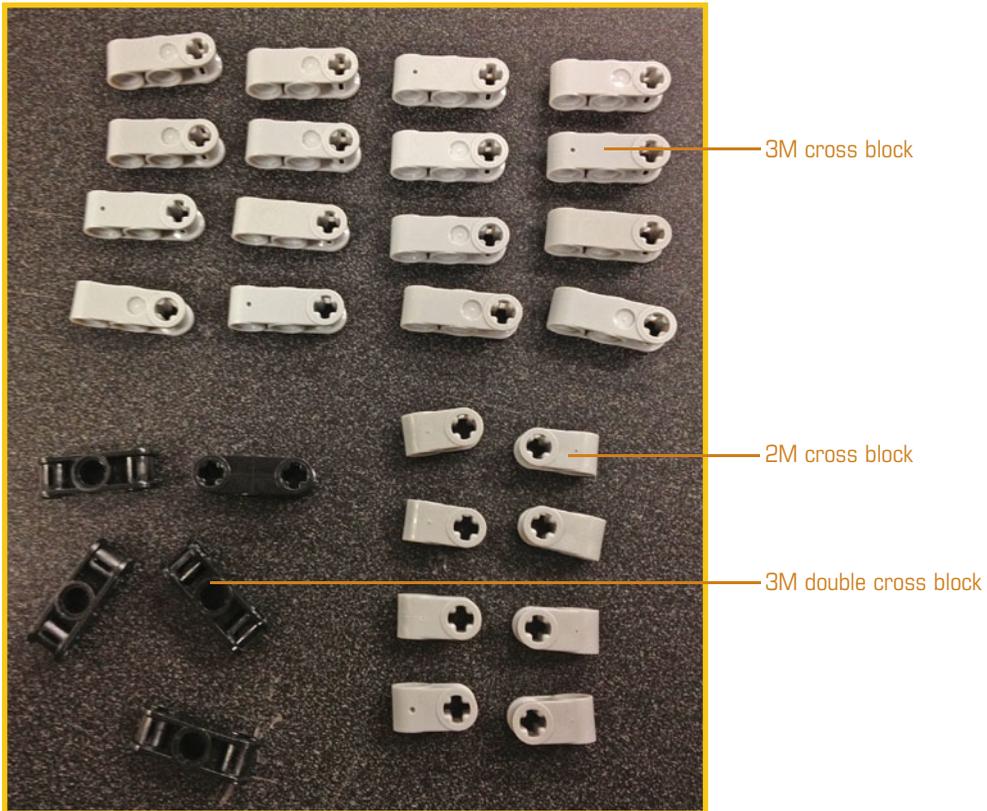


**FIGURE 1.27** Cross-axle connectors make long axles out of short ones.

## Cross Blocks

The parts shown in Figure 1.28 are called *cross blocks*, small beams with cross holes and Technic holes at right angles to each other. These parts allow you to attach cross axles to beams and to add perpendicular elements to help reinforce beam structures. I use the double cross blocks all the time; I don't know why LEGO includes only five in the set.

- 3M cross blocks—16
- 2M cross blocks—8
- 3M double cross blocks—5



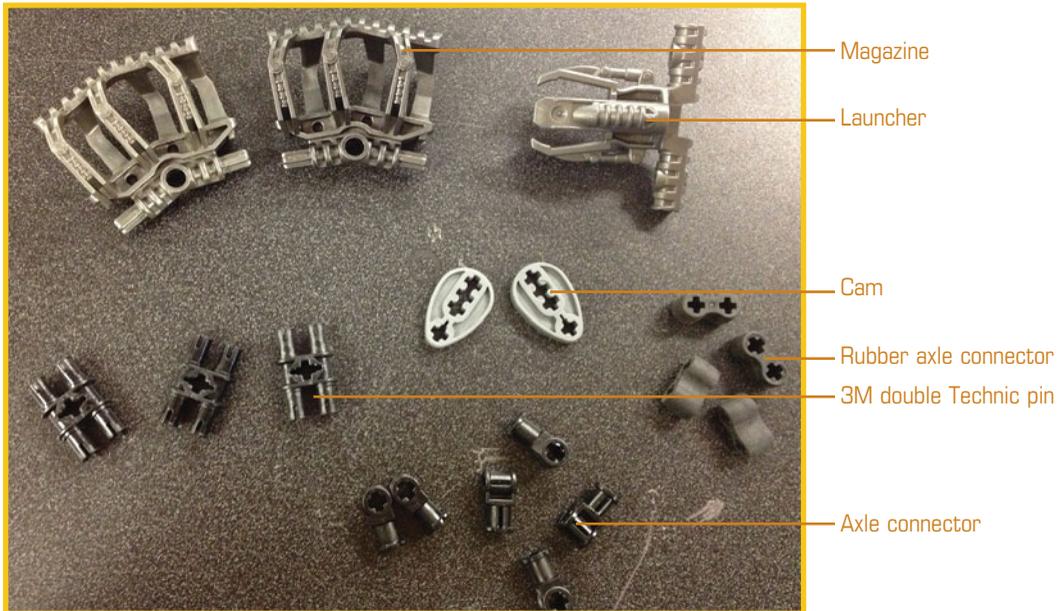
**FIGURE 1.28** Cross blocks allow you to add cross-holes to beams, and at different angles.

## More Miscellaneous Parts

More obscure parts! The funny-looking ones at the top of Figure 1.29 are the *magazine* and *launcher* for the ShooterBot, one of the robots you can build with the set; the instructions may be found on the Mindstorms software.

The black double pins are exactly that; you get three. The oval disks, called *cams*, are used to add an irregular motion to a motor's spin, and the four rubber things are called *rubber axle connectors*. Here's a breakdown of the oddball parts:

- Magazine—2
- Launcher—1
- 3M double Technic pin—3
- Cam—2
- Rubber axle connector—4
- Axle connector—6

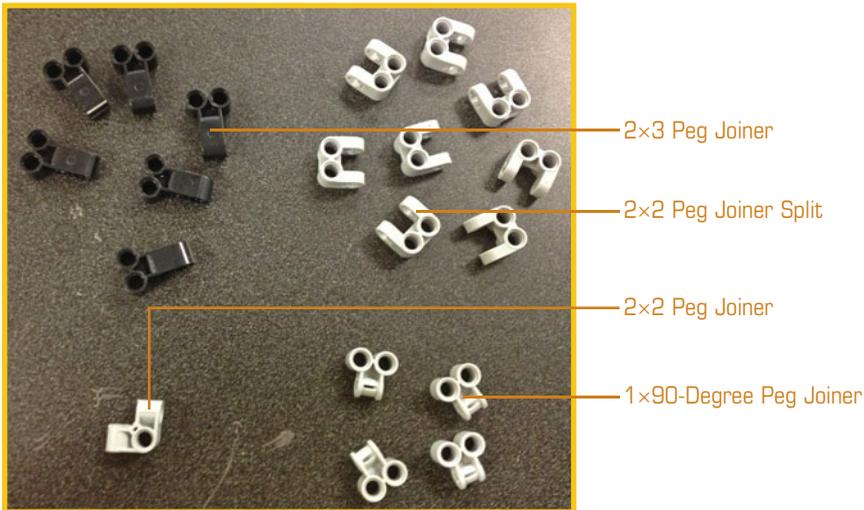


**FIGURE 1.29** Some parts are hard to categorize. Here are some of the more obscure parts found in the set.

## Peg Joiner

*Peg joiners* do just that, allowing you to insert connector pegs at different angles (see Figure 1.30). These parts are great for reinforcing your robot, especially if you've already built the bot and it's a little wobbly. Just reinforce the wobbly parts with some of these connectors!

- 2×3 peg joiner—6
- 2×2 peg joiner split—8
- 2×2 peg joiner—4
- 90-degree peg joiner—1



**FIGURE 1.30** Peg joiners are great for reinforcing wobbly robots.

## WHAT'S WITH THAT LITTLE WHITE TILE?

It may surprise readers that LEGO included one of their classic System bricks—a white 1x2 smooth plate, shown in Figure 1.31—in the Mindstorms set. It's hard to say why it was included; it's not exactly a useful piece because it attaches via studs and none of the Technic elements in the set have studs. It's a mystery!



**FIGURE 1.31** Who is to say why this one non-Technic Lego element was included?

## Motors, Wires, and Sensors

The larger of the two white boxes in the main set holds all your motors and sensors, as well as the Mindstorms wires and the USB cable you use to program your NXT brick. You get three interactive servo motors, two touch sensors, a color sensor, and an ultrasonic sensor (see Figure 1.32).



**FIGURE 1.32** This box contains the sensors, motors, and wires you'll need to turn a model into a robot!

### Ultrasonic Sensor

Let's take a peek at the ultrasonic sensor that comes with the set. As you can see in Figure 1.33, the ultrasonic sensor has two grills in the front, one of which covers a sensing element, while the other one emits sound. The idea is that the sensor beams out inaudible sound waves and then measures how fast the sound bounces back to the sensor, enabling you to measure distance with surprising accuracy.



**FIGURE 1.33** Ultrasonic sensors emit sound waves that help your bot measure distance.

### Touch Sensors

The Mindstorms touch sensors double as both pushbuttons as well as sensor-detecting contacts (see Figure 1.34). The sensors can discern three different actions: a quick bump, a press-and-hold, and a release action. You get two touch sensors with the set.



**FIGURE 1.34** Touch sensors can serve as a pushbutton or as a contact sensor.

### Interactive Servo Motors

Three of LEGO's interactive servo motors come with the set, and you'll probably wish there were more (see Figure 1.35). What differentiates them from motors one might find in a hobby store is that they are equipped with position encoders that enable the NXT brick to accurately determine the speed and precise angle of the motor's turn.



**FIGURE 1.35** Three interactive servo motors are included with the NXT 2.0 set.

### Color Sensor

The color sensor shown in Figure 1.36 can distinguish between colors—hence the name—but it does so much more. For instance, it not only can determine the color of a scanned object by bouncing a light off it and measuring the returned values but also can detect the level of lighting in a room (dark, poorly lit, bright, and so on). If that weren't enough, you can turn it into a lamp shining red, blue, and green lights. The color sensor is a vast improvement over the previous Mindstorms set, which only boasted a light sensor.



**FIGURE 1.36** The color sensor is a multipurpose part that you'll find many ways to use.

## USB Cable

LEGO includes a standard USB cable with the set (see Figure 1.37). It's fairly universal, so if you lose yours, you can always find another without buying an official LEGO product. You'll need this cable when you start programming your NXT brick.



**FIGURE 1.37** Use the supplied USB cable when you start programming your NXT brick.

## Mindstorms Wires

The Mindstorms sensors and motors communicate with the NXT brick with the help of six-ply wires (see Figure 1.38). The set comes with the following selection of wires, giving you a nice variety for all your projects:

- 20cm wire—1
- 35cm wires—4
- 50cm wires—2



**FIGURE 1.38** These wires carry the communications from the NXT brick to your bot's motors and sensors.

## The NXT Brick

The *NXT brick* is the brain of the robot, a computer that interprets data from the sensors and sends power to the motors to make them turn (see Figure 1.39). You learn all about the NXT brick in Chapter 3, “Anatomy of the NXT Brick,” so be sure to check it out!



**FIGURE 1.39** The NXT brick—the brain of your creations.

## Next Chapter

In Chapter 2, “Project: Backscratcher Bot,” we’ll build our first bot—the backscratcher bot!

# Index

## Numbers

---

- 1/2 connector pegs, 16
- 2M axle pegs, 14
- 3D printing, 192-193
- 3M connector pegs, 12-13
- 3M cross axles, Backscratcher Bot project, 43
- 5M beams, Backscratcher Bot project, 47
- 5M cross axles, Backscratcher Bot project, 44
- 7M beams, Backscratcher Bot project, 46
- 15M beams, Backscratcher Bot project, 46

## A

---

- action figures (minifigs), 121
- additional parts, finding
  - 3D printing, 192-193
  - BrickLink website, 189
  - LEGO Education website, 189
  - Pick a Brick website, 189
- third-party brick makers
  - Bricktronics website, 190

- Omni Wheels website, 190
- Tetrix Robotics website, 191
- Alpha Rex robot, building, 7-8
- angle beams, 24-25
  - Backscratcher Bot project, 45
  - stronger models, building, 124
- angle elements, 26
- arrow buttons (NXT bricks), 59
- artwork, LEGO Mindstorms NXT 2.0 box, 9
- axles
  - 2M axle pegs, 14
  - 3M cross axles, Backscratcher Bot project, 43
  - 5M cross axles, Backscratcher Bot project, 44
  - cross-axle connectors, 27
  - cross axles, 17
    - building stronger models, 125-126
    - cross axles with end stops, 18-19
  - rubber axle connectors, 28

## B

---

- Backscratcher Bot, building, 37
  - batteries, 38-39
  - NXT bricks
    - adding batteries to, 38-39
    - connections, 93
    - programming, 49-55, 92-93
    - required parts list, 40-42
    - running, 56
    - step-by-step build instructions, 42-48
- balls, 21
- Barometric sensors, 140
- batteries and NXT bricks, 38-39, 58, 77
- BayLUG website, 185
- beams
  - 5M beams, Backscratcher Bot project, 47
  - 7M beams, Backscratcher Bot project, 46
  - 15M beams, Backscratcher Bot project, 46
  - angle beams, 24-25
    - Backscratcher Bot project, 45

- building stronger models, 124
- beams with pegs, 22
- M numbers, 23
- Bionicle teeth, 21, 43
- blocks
  - Bluetooth blocks, 152
  - Constant blocks, 149
  - creating, 154-156
  - cross blocks, 27-28
    - Backscratcher Bot project, 45
    - building stronger models, 124-125
  - Display blocks, 152
  - Keep Alive blocks, 150-151
  - Light Sensor blocks, 151
  - Logic blocks, 153
  - Loop blocks, 88, 177-179
  - Move blocks, 89, 179-180
  - NXT-G blocks
    - Color Sensor blocks, 87
    - data hubs, 86
    - defining, 85
    - Loop blocks, 88
    - Move blocks, 89
    - NXT Buttons blocks, 89
    - programming blocks, 85
    - Switch blocks, 90
    - Ultrasonic Sensor blocks, 91
    - Wait blocks, 91
  - pallettes, 87
  - Random blocks, 150
  - Receive Message blocks (Bluetooth blocks), 152
  - Rotation Sensor blocks, 151
  - Send Message blocks (Bluetooth blocks), 152
  - Switch blocks, 90, 178
  - Variable blocks, 148-149
- blogs (LEGO-related), 181
- Bluetooth
  - Bluetooth blocks, 152
  - Bluetooth menu (NXT bricks), 73-77
  - connections, establishing, 77
  - NXT bricks, 58
- box (LEGO Mindstorms NXT 2.0)
  - artwork, 9
  - creative licensing and, 7
  - opening, 9
  - varying part quantities in, 11
- BrickCon, 186
- BrickFair, 186
- BrickJournal magazine, 188
- BrickLink website, 189
- brick makers (third-party)
  - Bricktronics website, 190
  - Omni Wheels website, 190
  - Tetrix Robotics website, 191
- bricks
  - chassis bricks, building stronger models, 128
  - NXT bricks, 35, 57
    - adding batteries to, 38-39
    - arrow buttons, 59
- Backscratcher Bot project, 48, 93
- batteries, 58, 77
- Bluetooth, 58, 73-77, 152
- connector holes, 61-62
- crashes, 78
- Display blocks and, 152
- Enter (orange) button, 59
- firmware updates, 78-79
- go back (gray) button, 59
- gray (go back) button, 59
- Keep Alive blocks and, 150-151
- My Files menu, 63-66
- naming, 58
- NXT Datalog menu, 70
- NXT Program menu, 66
- NXT Version item, 72
- orange (Enter) button, 59
- ports, 59-60
- powering, 77-78
- reset button, 62-63
- resetting, 78
- Running icon, 58
- Settings menu, 70-73
- shutoff switch, 77-78
- sleep feature, 72, 77
- Try Me menu, 67
- USB, 58
- View menu, 68-70

System bricks  
 building stronger models, 126-127  
 original LEGO system bricks, 30  
 Technic bricks, 126-127

Bricktronics website, 190

BrickWorld, 186

broken connections, gray wires and, 146

build competitions, 186-187

build instructions (step-by-step)  
 Backscratcher Bot, 42-48  
 Clothesline Cruiser, 97, 102, 113, 119  
 Rebounder robot, 159-161, 166, 170, 173-175

bumps (Touch sensors), 132

bushings, 16  
 Backscratcher Bot project, 44  
 connector pegs with bushings, 13

## C

---

CAD (computer-aided design) programs, LDD, 183-184

calibrating  
 blocks, 137  
 sensors, 136

cams, 28

car parts, 25

chassis bricks, building stronger models, 128

Clothesline Cruiser  
 parts needed, 96  
 programming, 119

setting up, 120

step-by-step build instructions, 97, 102, 113, 119

Touch sensors, 95

ultrasonic sensors, 95

uses for, 121

color  
 Color Sensor blocks (NXT-G), 87  
 color sensors, 31-33  
 availability of, 134  
 color lamps, 133  
 LEGO Mindstorm NXT 2.0 parts, 10

combination parts, building stronger models, 124-125

Common Palette, 87

compass sensors, 138

competitions (build), 186-187

Complete Palette, 87

Configuration panel (Mindstorms work area), 87

connections  
 broken connections and gray wires, 146  
 multiple connections, building stronger models, 123

connector holes, NXT bricks, 61-62

connector pegs, 11  
 1/2 connector pegs, 16  
 3M connector pegs, 12-13  
 Backscratcher Bot project, 45-46  
 connector pegs with bushings, 13

connector pegs with towballs, 15

Constant blocks, 149

conventions/gatherings  
 BrickCon, 186  
 BrickFair, 186  
 BrickWorld, 186  
 LUGs, 185

corners (reinforced), building strong models, 124

crashes (NXT bricks), resetting from, 78

Create My Block, 154

cross axles, 17, 27  
 3M cross axles, Backscratcher Bot project, 43  
 5M cross axles, Backscratcher Bot project, 44  
 cross axles with end stops, 18-19  
 stronger models, building, 125-126

cross blocks, 27-28  
 Backscratcher Bot project, 45  
 stronger models, building, 124-125

cross connectors, 14

cross holes, 14

Custom Palette, 87

## D

---

data hubs, 86

datalog files (NXT brick My Files menu), 66

data wires  
 connecting, 147  
 gray wires, 146

- green wires, 144
- orange wires, 145-146
- physical wires vs., 143
- yellow wires, 145
- Delete Files option (NXT bricks), 73
- deleting
  - files
    - replacing deleted files, 73
    - Settings menu (NXT bricks), 71
  - preflight files, 84
  - sound files, 65
- diagnostics, View menu (NXT bricks), 68
- dIMU (Inertial Motion) sensor, 140
- Display blocks, 152
- downloading programming, Backscratcher Bot, 94

---

## E - F

- end stops (cross axles with), 18-19
- Enter (orange) button (NXT bricks), 59
- figures (minifigs), 121
- files (NXT brick My Files menu)
  - datalog files, 66
  - NXT files, 65
  - software files, 64
  - sound files, 65-66
- finding
  - additional parts
    - 3D printing, 192-193
    - BrickLink website, 189
    - Bricktronics website, 190

- LEGO Education
  - website, 189
- Omni Wheels
  - website, 190
- Pick a Brick
  - website, 189
- Tetrix Robotics
  - website, 191
- Universal Connector
  - Kit, 193
- Technic bricks
  - online, 127
- firmware updates, NXT bricks, 78-79
- Flex sensors, 139
- FLL (FIRST LEGO League), 186-187
- further reading
  - BrickJournal magazine, 188
  - Mindstorms website, 182
  - NXT STEP blog, 181

---

## G

- gatherings/conventions
  - BrickCon, 186
  - BrickFair, 186
  - BrickWorld, 186
  - LUGs, 185
- gears, 20
- gray (go back) button (NXT bricks), 59
- gray wires, 146
- green wires, 144

---

## H

- half bushings, 16
- help
  - BrickJournal magazine, 188

- LEGO Mindstorms User
  - Guide, 10
- Mindstorms User
  - Guide, 49
- Mindstorms website, 182
- NXT STEP blog, 181
- programming, trouble-shooting, 94
- Help window (Mindstorms work area), 87
- holes
  - connector holes (NXT bricks), 61-62
  - cross holes, 14
  - Technic holes, 14

---

## I

- Inertial Motion sensors, 140
- Infrared (PIR) sensors, 138
- installing NXT-G
  - Mac installations, 84-85
  - PC installations, 83-84
- instructions (step-by-step)
  - Backscratcher Bot, 42-48
  - Clothesline Cruiser, 97, 102, 113, 119
  - Rebounder robot, 159-161, 166, 170, 173-175
- interactive servo motors, 32

---

## J - K - L

- joiners (peg), 29
- Keep Alive blocks, 150-151
- launchers (ShooterBot), 28
- LDD (LEGO Digital Designer), 183-184

legged robots, Touch sensors, 132

LEGO Education website, 189

LEGO Mindstorms NXT 2.0 box

- artwork, 9
- creative licensing and, 7
- opening, 9
- varying part quantities in, 11

LEGO Mindstorms User Guide, 10

length. *See* M numbers

Leopard (Mac OS 10.5), NXT-G installations, 85

lifarms, Backscratcher Bot project, 46

Light Sensor blocks, 151

Linux, NXT-G system requirements, 82

Logic blocks, 153

Logic data and green wires, 144

Loop blocks

- NXT-G, 88
- Rebounder robot, 177-179

LUGs (LEGO User Groups), 185

## M

M numbers, 17

- 2M axle pegs, 14
- 3M connector pegs, 12-13
- 3M cross axles, Backscratcher Bot project, 43
- 5M cross axles, Backscratcher Bot project, 44

beams, 23

- 5M beams, Backscratcher Bot project, 47
- 7M beams, Backscratcher Bot project, 46
- 15M beams, Backscratcher Bot project, 46

cross axles

- 3M cross axles, Backscratcher Bot project, 43
- 5M cross axles, Backscratcher Bot project, 44

Macs, NXT-G installations

- Leopard (10.5) installations, 85
- preflight files, 84
- Snow Leopard (10.6) installations, 85
- system requirements, 82

magazines (LEGO-related)

- BrickJournal, 188
- ShooterBot, 28

Magnetic sensors, 139

menus (NXT bricks)

- Bluetooth menu, 73-77
- My Files menu, 63
  - datalog files, 66
  - NXT files, 65
  - software files, 64
  - sound files, 65-66
- NXT Datalog menu, 70
- NXT Program menu, 66
- Settings menu, 70
  - Delete Files option, 73
  - Volume menu, 71
- Try Me menu, 67

View menu, 68-70

Volume menu, 71

Mindstorms software

- Clothesline Cruiser, programming, 119
- Mindstorms User Guide, 49
- Mindstorms website, 182
- Rebounder robot, programming, 176-180
- welcome screen, 82
- work area, 86-87

minifigs, 121

models (virtual), LDD, 183-184

motion sensors (Inertial), 140

motors, 31

- Backscratcher Bot project, 46
- interactive servo motors, 32
- NXT brick ports, 60
- sensors as, 135

Move blocks

- NXT-G, 89
- Rebounder robot, 179, 180

multiple connections, building stronger models, 123

multiple pegs, building stronger models, 123

My Files menu (NXT bricks), 63

- datalog files, 66
- NXT files, 65
- software files, 64
- sound files, 65-66

My Portal (Mindstorms work area), 87

## N

naming NXT bricks, 58  
 NCLUG website, 185  
 NELUG website, 185  
 Number data and yellow wires, 145  
 NXT bricks, 35, 57  
   arrow buttons, 59  
   Backscratcher Bot project, 48, 93  
   batteries, 38-39, 58  
   Bluetooth, 58, 73-77, 152  
   connector holes, 61-62  
   crashes, resetting from, 78  
   Display blocks and, 152  
   Enter (orange) button, 59  
   firmware updates, 78-79  
   gray (go back) button, 59  
   Keep Alive blocks and, 150-151  
   menus  
     Bluetooth menu, 73-77  
     My Files menu, 63-66  
     NXT Datalog menu, 70  
     NXT Program menu, 66  
     Settings menu, 70-73  
     Try Me menu, 67  
     View menu, 68-70  
   naming, 58  
   NXT Version item, 72  
   orange (Enter) button, 59  
   ports, 59-60

powering  
   batteries, 77  
   shutoff switch, 77-78  
   sleep feature, 77  
 reset button, 62-63  
 Running icon, 58  
 sleep feature, 72, 77  
 USB, 58  
 NXT Buttons blocks (NXT-G), 89  
 NXT controller (Mindstorms work area), 87  
 NXT Datalog menu (NXT bricks), 70  
 NXT files (NXT brick My Files menu), 65  
 NXT-G  
   Backscratcher Bot, programming, 92  
   blocks  
     data hubs, 86  
     defining, 85  
   Clothesline Cruiser, programming, 119  
   Color Sensor blocks, 87  
   Linux system requirements, 82  
   Loop blocks, 88  
 Macs  
   installing on, 84-85  
   Leopard (10.5) installations, 85  
   Snow Leopard (10.6) installations, 85  
   system requirements, 82  
 Move blocks, 89  
 NXT Buttons blocks, 89  
 PCs  
   installing on, 83-84  
   system requirements, 82

programming blocks, 85  
 Rebounder robot, programming, 176-180  
 Switch blocks, 90  
 Ultrasonic Sensor blocks, 91  
 Wait blocks, 91  
 NXT Program menu (NXT bricks), 66  
 NXT STEP blog, 181  
 NXT Version item (NXT bricks), 72

## O - P

Omni Wheels website, 190  
 orange (Enter) button (NXT bricks), 59  
 orange wires, 145-146  
 pallettes  
   Common Palette, 87  
   Complete Palette, 87  
   Custom Palette, 87  
 parts (additional), finding  
   3D printing, 192-193  
   BrickLink website, 189  
   LEGO Education website, 189  
   Pick a Brick website, 189  
 third-party brick makers  
   Bricktronics website, 190  
   Omni Wheels website, 190  
   Tetrix Robotics website, 191  
 PCs, NXT-G installations, 82-84  
 peg joiners, 29

pegs  
 2M axle pegs, 14  
 3M connector pegs,  
 12-13  
 beams with pegs, 22  
 connector pegs, 11  
 1/2 connector  
 pegs, 16  
 3M connector pegs,  
 12-13  
 Backscratcher Bot  
 project, 45-46  
 connector pegs with  
 bushings, 13  
 connector pegs with  
 towballs, 15  
 cross connectors, 14  
 multiple pegs, building  
 stronger models, 123  
 permissions, NXT-G PC  
 installations, 84  
 Pick a Brick website, 189  
 pins (Technic), 28  
 PIR (Passive Infrared) sen-  
 sors, 138  
 ports (NXT bricks), 59-60  
 powering NXT bricks  
 batteries, 77  
 shutoff switch, 77-78  
 preflight files, deleting, 84  
 presses (Touch  
 sensors), 132  
 printing (3D), 192-193  
 programming  
 Backscratcher Bot, 49-55  
 creating program-  
 ming, 92  
 downloading pro-  
 gramming, 94  
 NXT brick connec-  
 tions, 93

calibrating blocks, 137  
 Clothesline Cruiser, 119  
 Rebounder robot,  
 176-180  
 troubleshooting, 94  
 programming blocks  
 (NXT-G), 85

## R

Random blocks, 150  
 reading  
 BrickJournal  
 magazine, 188  
 BrickLink website, 189  
 LEGO Mindstorms User  
 Guide, 10  
 Mindstorms User  
 Guide, 49  
 NXT STEP blog, 181  
 ShooterBot magazine, 28  
 Rebounder robot, 157  
 Loop blocks, 177-179  
 Move blocks, 179-180  
 parts needed, 158  
 programming, 176-180  
 step-by-step build  
 instructions, 159-161,  
 166, 170, 173-175  
 Switch blocks, 178  
 tank treads, 175  
 Receive Message blocks  
 (Bluetooth blocks), 152  
 rechargeable batteries, NXT  
 bricks, 77  
 reinforced corners, building  
 stronger models, 124  
 releases (Touch  
 sensors), 132  
 replacing deleted files, 73  
 reset button (NXT bricks),  
 62-63

resetting NXT bricks, 78  
 rims and tires, 19  
 RoboCenter (Mindstorms  
 work area), 87  
 Rotation Sensor blocks, 151  
 rubber axle connectors, 28  
 Running icon (NXT  
 bricks), 58

## S

Send Message blocks (Blue-  
 tooth blocks), 152  
 sensors, 131  
 Barometric sensors, 140  
 calibrating, 136-137  
 Color sensors, 31-33  
 availability of, 134  
 color lamps, 133  
 compass sensors, 138  
 dIMU, 140  
 Flex sensors, 139  
 Inertial Motion  
 sensors, 140  
 Magnetic sensors, 139  
 motion (Inertial), 140  
 motors as, 135  
 NXT brick ports, 60  
 PIR sensors, 138  
 Sound sensors, 134  
 Touch sensors, 31-32,  
 95, 132  
 Ultrasonic sensors, 31,  
 95, 133  
 voltage sensors, 140  
 VoltMeter, 140  
 Wi-Fi sensors, 138  
 sequence beams (Mind-  
 storms work area), 87  
 servo motors  
 (interactive), 32

Settings menu (NXT bricks), 70

- Delete Files option, 73
- Volume menu, 71

ShooterBot magazine, 28, 49

shutoff switch (NXT bricks), 77-78

sleep feature (NXT bricks), 72, 77

Snow Leopard (Mac OS 10.6), NXT-G installations, 85

software files (NXT brick My Files menu), 64

sound files

- NXT brick My Files menu), 65-66
- Volume menu (NXT bricks), 71

Sound sensors, 134

starting point (Mindstorms work area), 87

steering links, 26

stronger models, building techniques

- angle beams, 124
- chassis bricks, 128
- combination parts, 124-125
- cross axles, 125-126
- cross blocks, 124-125
- multiple connections, 123
- multiple pegs, 123
- reinforced corners, 124
- System bricks, 126-127
- Technic bricks, 126-127

Switch blocks

NXT-G, 90

Rebounder robot, 178

System bricks

- original LEGO system bricks, 30
- stronger models, building, 126-127

system requirements (NXT-G)

- Linux, 82
- Macs, 82
- PCs, 82

---

## T

tank treads, 19, 175

Technic bricks

- stronger models, building, 126-127
- web resources, 127

Technic holes, 14

Technic pins, 28

teeth (Bionicle), 21, 43

Tetrix Robotics website, 191

Text data and orange wires, 145-146

third-party brick makers

- Bricktronics website, 190
- Omni Wheels website, 190
- Tetrix Robotics website, 191

tires and rims, 19

toolbar (Mindstorms work area), 87

tooth gears, 20

ToroLUG website, 185

Touch sensors, 31-32, 95, 132

towballs, connector pegs with, 15

treads, 19

troubleshooting programming, 94

Try Me menu (NXT bricks), 67

TwinLUG website, 185

---

## U

ultrasonic sensor, 31

Ultrasonic Sensor blocks (NXT-G), 91

Ultrasonic sensors, 95, 133

Universal Connector Kit, 193

updating NXT brick firmware, 78-79

USB

- NXT brick ports, 59-60
- NXT bricks, 58
- USB cable, 31, 34

user profile (Mindstorms work area), 87

---

## V

Variable blocks, 148-149

versioning, NXT Version item (NXT bricks), 72

View menu (NXT bricks), 68-70

virtual models, LDD, 183-184

voltage sensors, 140

VoltMeter, 140

Volume menu (NXT bricks), 71

## W

---

Wait blocks (NXT-G), 91

web resources, Technic bricks, 127

websites

BayLUG, 185

BrickLink, 189

Bricktronics, 190

LEGO Education, 189

NCLUG, 185

NELUG, 185

Omni Wheels, 190

Pick a Brick, 189

Tetrix Robotics, 191

ToroLUG, 185

TwinLUG, 185

Universal Connector Kit, 193

welcome screen (Mindstorms software), 82

wheels, 19, 190

Wi-Fi sensors, 138

Windows. *See* PCs

wires, 31, 35

Backscratcher Bot project, 48

data wires, 143

connecting, 147

gray wires, 146

green wires, 144

orange wires, 145-146

yellow wires, 145

Mindstorms work area, 87

physical wires, 143

work area (Mindstorms), 86-87

## X - Y - Z

---

yellow wires, 145